

## Collision Avoidance Subcommittee Update

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#### **SPE ACR Adoption Status**

- 16 Attendees 6 Yes (5 orgs) Higher percentage than previous meetings
  - Oxy
  - Baker-Hughes
  - Schlumberger (DrillPlan)
  - Dynamic Graphics (WellArchitect)
  - Halliburton/Landmark (Compass)

#### **Review of Outstanding Actions**

- Update Documentation Bibliography / Lexicon / Merge efforts with other groups
- Sidetrack handling CA diagnostics files and Rev 5 update of benchmarks
- Collision Avoidance Reporting Standardization
- Standard Rule Guidance memo modification of Sm & Pa
- Inferred Wellbore Position a committee formed
- Guidance on Survey Interval in relation to Collision Avoidance \*\*New \*\*

#### **CA Survey Interval Guidance**

OWSG Request for Review / Guidance

# CA Survey Interval – SPE-184730 Well Collision Avoidance Management Principles

*Surveying Interval.* The following recommendations for the maximum survey interval are intended only for safe-separation and collision avoidance, Table 3. They do not address the requirements for routine drilling and meeting other well objectives such as targets. To be valid, all surveys are required to pass the quality control criteria appropriate to the survey tools and the applied IPMs. In general, the survey frequency increases with increasing dog-leg severity (DLS) and decreasing SF. The intervals may be adjusted for non-standard tool joints or stands (Double, Triple, Quad and Range I, II, III). The intervals may also be extended where the continued divergence of the reference well from all the offset wells has been firmly established.

Table 3—Recommended maximum survey interval for safe-separation and collision avoidance

| Maximum<br>Survey<br>Interval [ft] |         | DLS [deg/100ft MD] |     |    |
|------------------------------------|---------|--------------------|-----|----|
|                                    |         | <1                 | 1-5 | >5 |
| SF [-]                             | >2      | 200                | 100 | 33 |
|                                    | 1.5 – 2 | 100                | 100 | 33 |
|                                    | <1.5    | 33                 | 33  | 33 |



### Current RP 78 Recommended Survey Interval

| Maximum Survey Interval [ft] |         | Planned DLS [deg/100ft MD] |     |     |  |
|------------------------------|---------|----------------------------|-----|-----|--|
|                              |         | < 1                        | 1-5 | > 5 |  |
|                              | > 2     | 200                        | 100 | 33  |  |
| SF [-]                       | 1.5 - 2 | 100                        | 100 | 33  |  |
|                              | < 1.5   | 33                         | 33  | 33  |  |



### Proposed RP 78 Recommended Survey Interval

| Maximum Survey | Planned DLS [deg/100ft MD]           |               |                      |  |
|----------------|--------------------------------------|---------------|----------------------|--|
| Interval [ft]  | < 2°/100ft                           | 2° – 6°/100ft | 6°/100ft             |  |
|                | Tangent                              | Long Radius   | <b>Medium Radius</b> |  |
| SF > 4         | Follow Regulatory Requirements (FRR) |               |                      |  |
| 1.25 < SF < 4  | 200 ft or FRR                        | 100 ft        | 100 ft               |  |
| 1 < SF < 1.25  | 100 ft                               | 100 ft        | Joint                |  |
| SF < 1         | 100 ft                               | Joint         | Joint                |  |

#### Survey Interval - Conclusion

- RP-78 Will adopt the proposed table of recommendations
- Ongoing investigation between Error Model and Collision Avoidance subcommittees

#### WPTS Standard Collision Avoidance Separation Rule

 Validation of magnitude values for Surface Margin & Project Ahead uncertainty – guidance

$$k = 3.5$$
,  $S_m = 0.3$ m and  $\sigma_{pa} = 0.5$ m.

$$SF = \frac{D - R_r - R_o - S_m}{k\sqrt{\sigma_s^2 + \sigma_{pa}^2}}$$

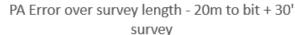
$$SF = \frac{D - R_r - R_o - 0.3}{3.5\sqrt{\sigma_s^2 + 0.25}}$$

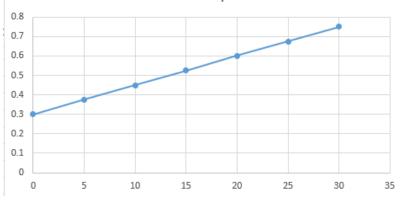
 Jerry Codling – Survey of Operators/Contractors Existing Rules – Surface Handling

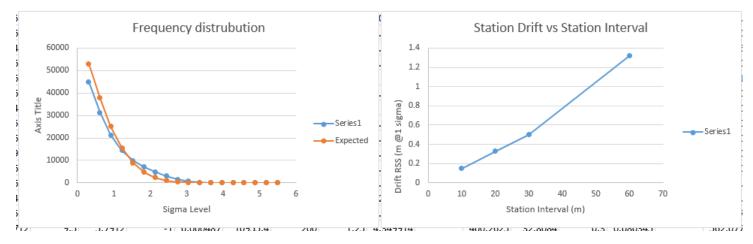


Wellbore Positioning Technica

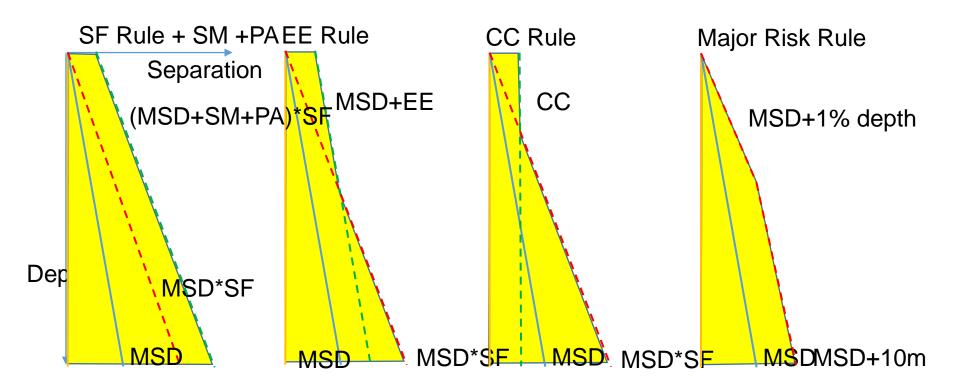
- Value of 0.5m seems to be close to expected error for motor assembly and 90' station intervals
- But can justify smaller values if using RSS (near bit sensors) and continuous or 30' measurements











 $MSD=k^*(sum errors)+R1+R2$ 

#### WPTS Standard Collision Avoidance Separation Rule

- Recommendation & Action Create Addendum Document
  - Advise that standard rule can be used as-is if provided Sm/Pa constants work for your organization
  - Advise that Sm can be set to zero if used in conjunction with another means of accounting for surface collision avoidance mitigation
  - Advise the Pa value can be changed to a smaller value if specific operations use a smaller survey interval – as per chart
  - Continue with Zoom/Teams meeting to produce first draft next 1-2 months

#### Collision Avoidance Reporting - Standardization

- Previous meeting (56/31 Houston) Defined 13 Columns
- This meeting (57/32 Stavanger) Start on Header items 1 hr group effort
- Some questions on the addition of columns and possible deletion of some
- Will have some continued Zoom/Teams meetings



#### CA Reporting Nomenclature Standardization – WORK

(robust discussion)

| # Full Description of Column   | Name                                  | Short Name | Value Type        |
|--|---------------------------------------|------------|-------------------|
| 1 Reference Well Measured Depth  | Reference MD                          | Ref MD     | length / distance |
| 2 Reference Well True Vertical Depth   | Reference TVD                         | Ref TVD    | length / distance |
| 3 Offset Well Measured Depth   | Offset MD                             | Off MD     | length / distance |
| 4 Offset Well True Vertical Depth  | Offset TVD                            | Off TVD    | length / distance |
| 5 Centerline to Centerline Wellbore Proximity  | Ct-to-Ct Distance                     | C-C        | length / distance |
| 6 Minimum Acceptable Separation Distance required to satisfy Collision Avoidance Rule    | Minimum Allowable Separation Distance | MASD       | length / distance |
| 7 Separation Factor  | Separation Factor                     | SF         | unitless          |
| 8 Travelling Cylinder North Azimuth  | Travelling Cylinder North Azimuth     | TC Azi.    | angle             |
| 9 Normal Plane Distance (Traveling Cylinder Plane)                                       | Normal Plane Distance                 | TC Dist.   | length / distance |
| 10 Allowable Distance from Reference Well that will satisfy Collision Avoidance Rule     | Allowable Deviation From Reference    | ADR        | length / distance |
|  |                                       |            | boolean           |
| 11 Orientation of Closest Approach relative to Reference Well's direction (Ahead/Behind) | Closest Approach Orientation          | Ang        | (ahead/behind)    |
| 12 Collision Avoidance Rule Status (Pass/Fail)   | CRA Status                            | Status     | boolean           |
| 13 Collision Avoidance Action Criteria   | Collision Avoidance Action            | Action     | free text         |
| 14 Active Rule   | Active Rule                           |            | text              |
| 15 Probability Of Collision  |                                       |            |                   |

## Thank You – Questions?