



MEMS MWD gyro (GDIS)Field test analysis

Ross Lowdon

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Speaker Bio

- Introduction
 - Schlumberger Drilling and Measurements
 - 20+ yrs in O&G industry 17 yrs in wellbore surveying
 - MSc in Drilling and Well Engineering
 - Houston
 - Specialized in
 - Wellbore surveying
 - Directional Drilling
 - Hydrographic surveying

GDIS field test results

Agenda

GMWD Field test
results presented by
Ross Lowdon

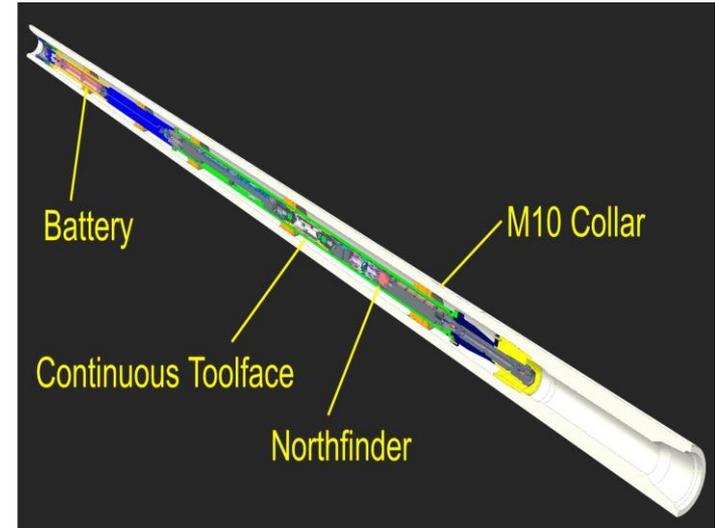
- GDIS Introduction
 - Calibration and QC
- GDIS test parameters
- GDIS field test results
 - Run Summary
 - GDIS QC
 - Survey comparison methodology
 - Definitive survey comparisons
- Conclusions and Further work

GDIS field test results

GDIS Introduction

GMWD Field test
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- GDIS
 - MEMS solid state gyro
 - Robust and low power
 - Traditionally low accuracy
 - 3 axis gyro reduced noise level
 - Accurate flipping mechanism
 - 2 minute survey time (Best survey pumped up)
 - Continuous TF during sliding (3 axis gyro)
 - Multiple surveys on every connection
 - Module based system
 - RPM/downlink/Pumps off survey triggers



GDIS field test results

GDIS Survey QC and Calibration

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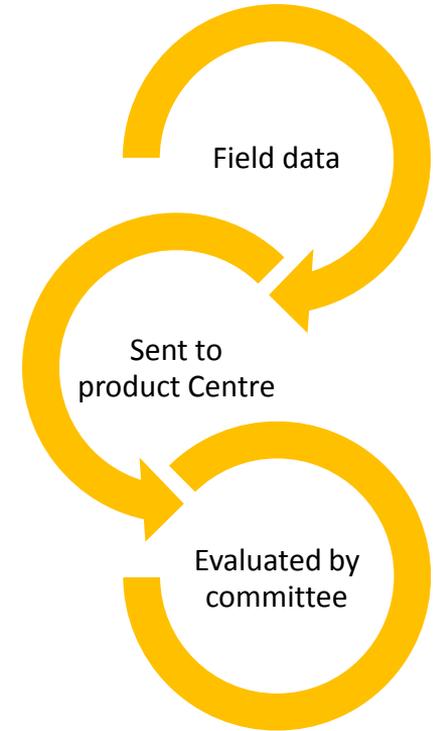
- QC
 - Earth Rate
 - Latitude
 - Standard deviation Indicator (through rotation cycle)
 - Shock & Vibration indicator
 - Standard Deviation
- Calibration
 - True North referenced stand
 - Tool rotated at known references
 - RT and HT

GDIS field test results

GDIS Test Parameters

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- GDIS Test parameters
 - Setting up for success
 - Run in memory mode
 - Run on platforms
 - Multiple locations
 - Variation in inclination and azimuth
 - Temp limitation
 - Develop empirical and lab based error model



GDIS field test results

GDIS run summary

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- 21 wells
- 26 runs
- 1300 operation hrs
- 110C max temp
- 95k ft drilled
- 1 mis-run



GDIS field test results

GDIS survey comparison methodology

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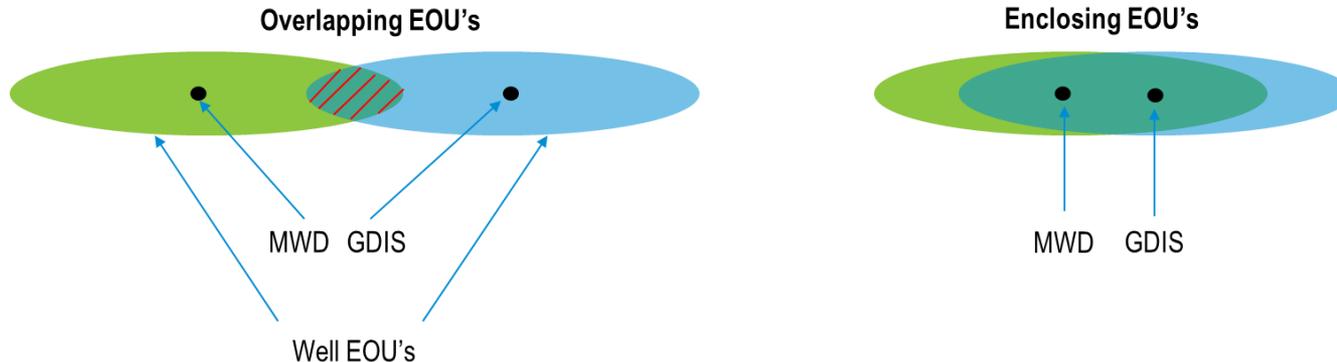
- Multiple surveys at connection
 - All QC accepted surveys averaged
- GDIS survey compared with Definitive surveys
 - Gyro and or MWD
- GDIS EOU's use GDIS empirical error model
 - Validated by the 19 and counting data sets processed
- Average delta's and Standard deviations reviewed
 - Systematic offsets and random noise

GDIS field test results

GDIS survey comparison methodology

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- EOU overlap and inclusion (EOU's similar sizes)
- Statistically EOU overlap = EOU verification
- Realistically EOU inclusion significantly improves confidence

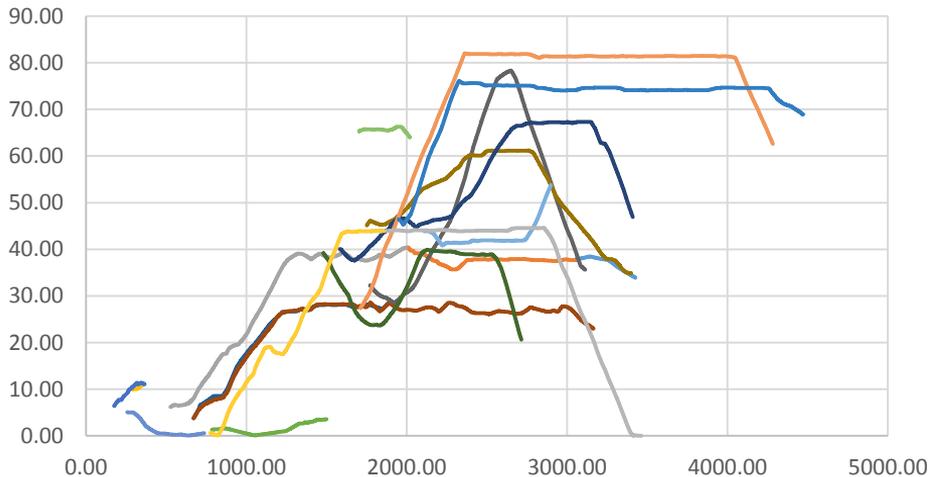


GDIS field test results

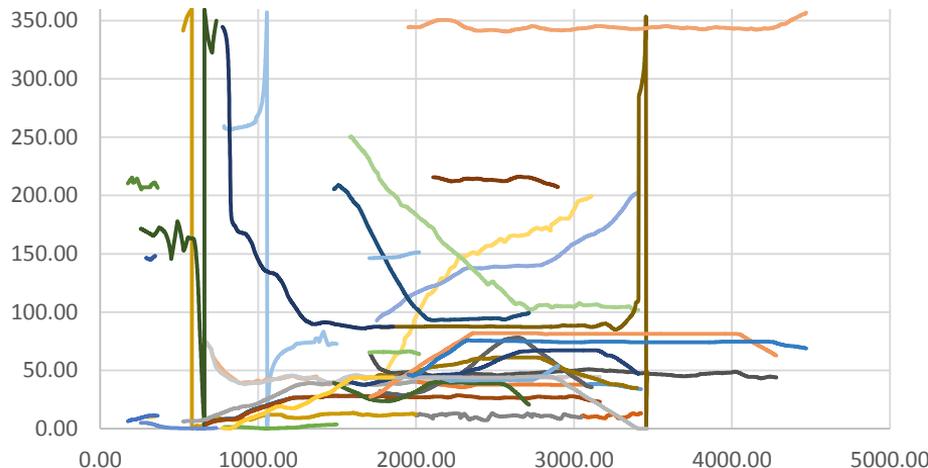
GDIS Run orientations and MD

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Inclination v MD



Azimuth v MD



GDIS field test results

GDIS definitive survey comparisons

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	Semi Maj	TVD error	Lateral Dist	TVD Dist	EOU Overlap	EOU inclusion	Incl AVE Delta	Incl STDEV	Azi AVE Delta	Azi STDEV
run 1	40.47	6.65	69.73	12.62	Yes	No	0.13	0.39	1.29	3.15
run 2	17.48	3.39	5.73	0.01	Yes	Yes	0.00	0.12	1.05	1.13
run 3	14.93	5.52	1.58	-1.48	Yes	Yes	-0.13	0.18	0.03	1.96
run 4	21.49	2.60	9.24	-2.53	Yes	Yes	-0.12	0.11	-0.12	1.96
run 5	23.61	3.45	9.55	0.00	Yes	Yes	0.00	0.12	-0.41	1.18
run 6	2.07	1.10	0.17	0.00	Yes	Yes	0.11	0.08	0.10	72.15
run 7	6.37	3.64	5.98	0.86	Yes	Yes	0.01	-0.24	0.42	1.26
run 8	21.65	6.35	7.36	0.64	Yes	Yes	0.03	0.09	-0.55	1.02
run 9	43.48	9.50	3.05	9.41	Yes	Yes	0.17	0.10	0.32	0.87
run 10	22.05	5.16	1.58	0.96	Yes	Yes	0.10	0.22	0.13	1.22
run 11	26.78	6.81	1.46	-1.33	Yes	Yes	-0.11	0.13	0.02	1.75
run 12	4.71	2.99	0.67	0.01	Yes	Yes	0.08	0.11	0.47	59.91
run 13	6.97	4.41	4.59	1.05	Yes	Yes	0.05	0.32	0.47	0.29
run 14	13.27	9.31	8.65	-0.32	Yes	Yes	0.02	0.18	0.55	0.76
run 15	1.35	1.14	1.87	-0.33	Yes	No	0.55	0.27	-0.86	2.03
run 16	1.02	1.12	0.28	-0.05	Yes	Yes	0.26	0.11	-0.09	1.46
run 17	6.97	4.41	5.22	1.05	Yes	Yes	0.10	0.18	0.43	0.70
run 18	9.24	7.07	8.50	-1.67	Yes	Yes	0.01	0.27	0.79	1.15
run 19	13.77	9.57	9.83	-1.12	Yes	Yes	-0.14	0.11	0.91	0.96

GDIS field test results

Conclusions

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- Accurate MEMS gyro while drilling
- GDIS data comparable with MWD and other gyro systems
- Reduced calibration requirement
- GDIS reliable and robust
- Scope for accuracy improvement

Further work

- Implement specific GDIS running procedures
- Add functionality